



WIND SPEED RETRIEVAL FROM DIGITAL COMMUNICATION AND GPS SIGNALS

Rashmi Shah, James Garrison, Nicole Quindara

Radio Navigation Laboratory

School of Aeronautics and Astronautics

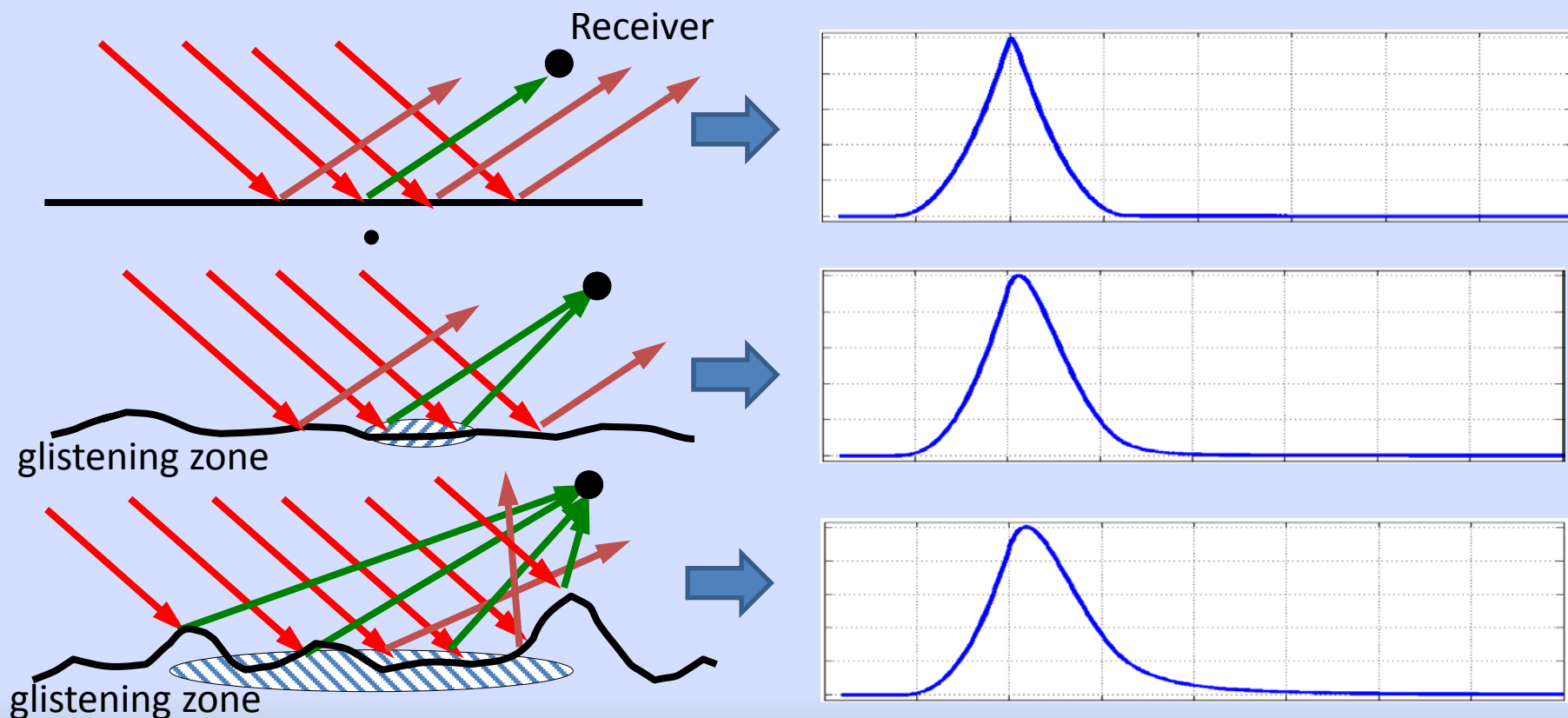
Purdue University

- **Background**
 - Past Heritage with GNSS-R
 - Motivation
- **Objective**
- **Recent Demonstration with S-Band Signals**
- **Retrievals from Simulation**
- **Description of Flight-Certified Instrument**
- **Summary and Future Work**

Ocean Roughness/Wind Speed

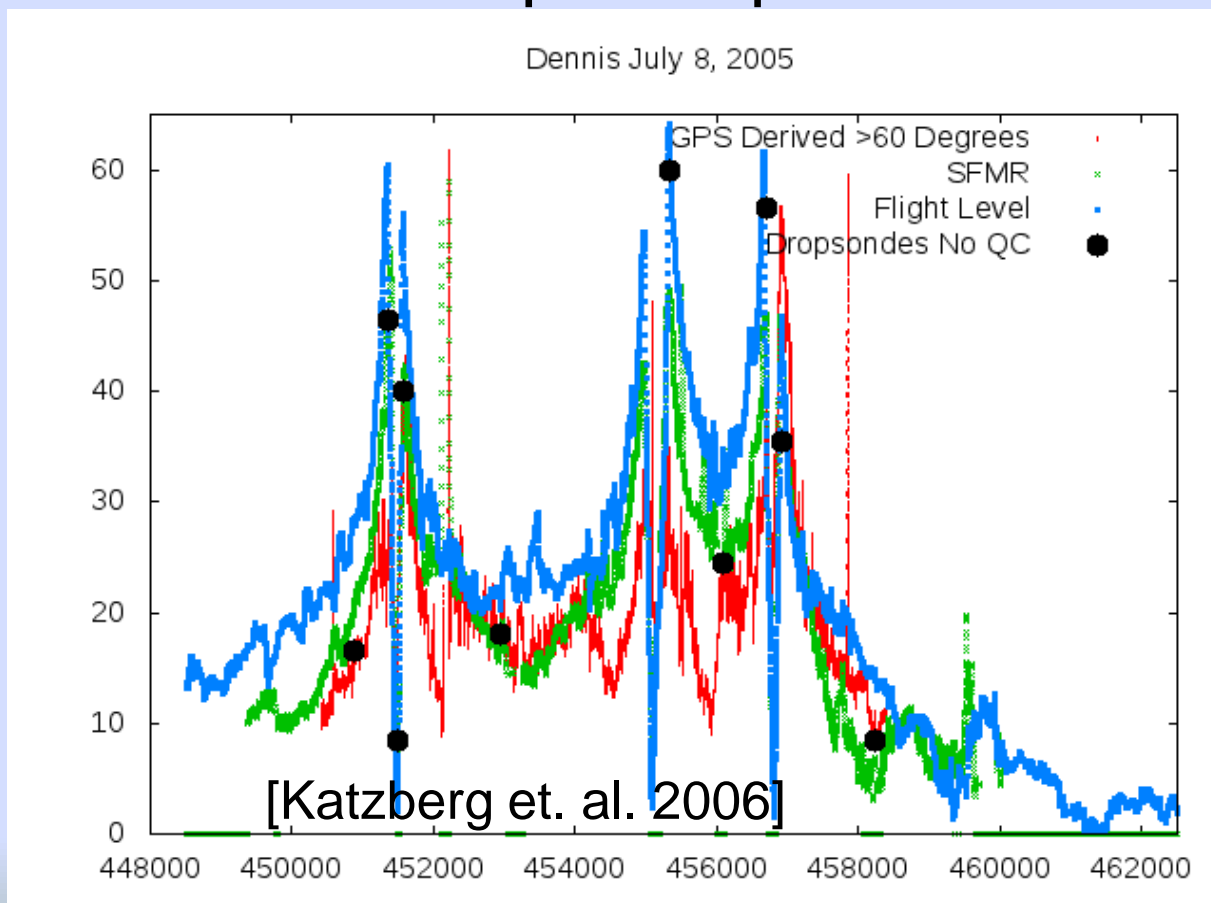
Fundamental Physics:

Rougher surface = larger distribution in path delays



GNSS-R Experience

- GNSS-R receivers on NOAA flights since 2000
- Calibration with wind speed up to Hurricane speeds.

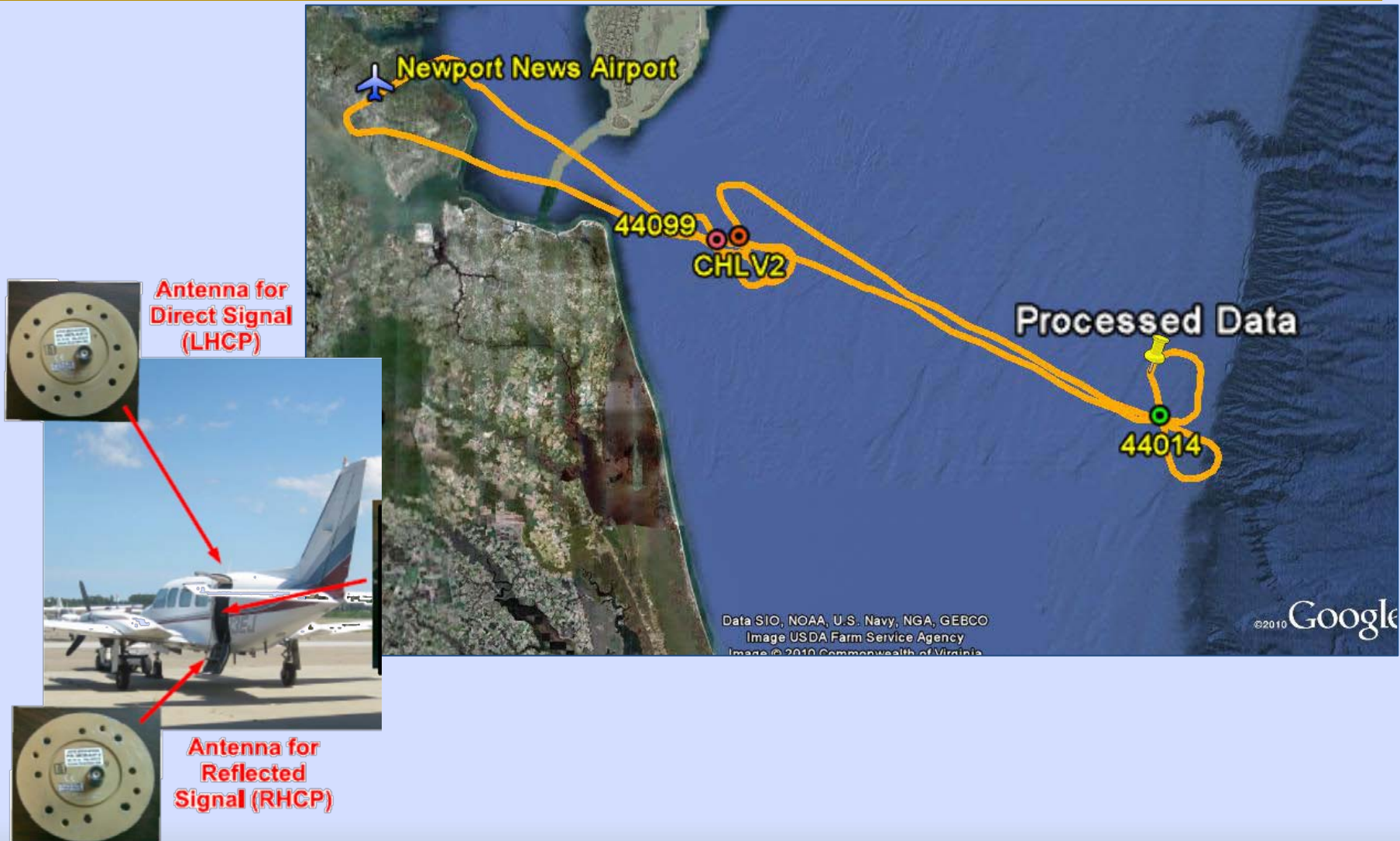


- **Why Digital Communication Signals?**
 - Noise-like transmission - generates range-bins
 - Free transmitters > 400 satellites
 - Higher transmitted power: Better accuracy
 - Geostationary orbit: Fixed geometry
 - Low-Cost receiver (all consumer electronics)
- **Demonstrated using XM radio signals (S-band)**

Objectives

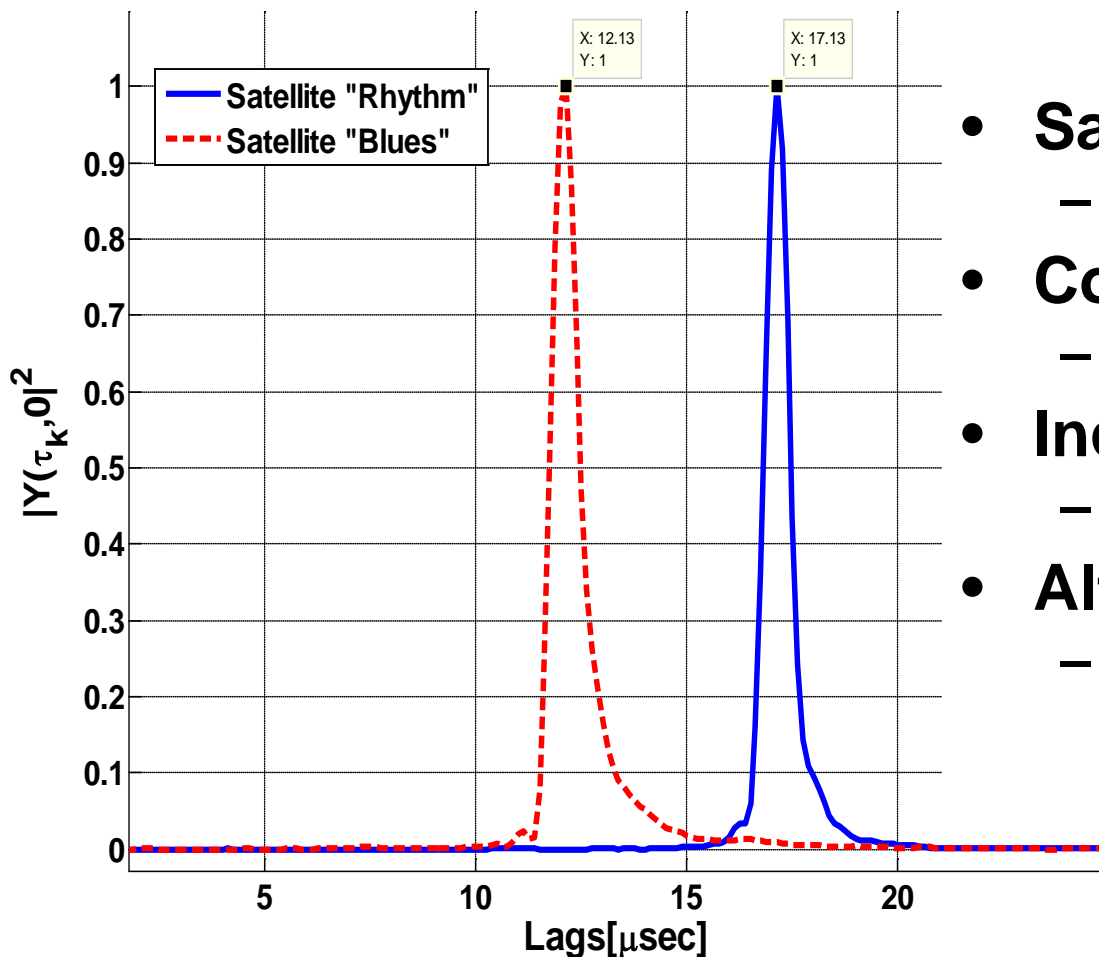
- To demonstrate reflectometry with digital communication signals
- To quantify wind speed retrieval error:
GPS vs. XM
- Plan for high-speed retrieval from XM instrument

2010 Experiment



Waveforms (2010)

Flight Result, $F_s = 8\text{MHz}$, Altitude = 3174 meters

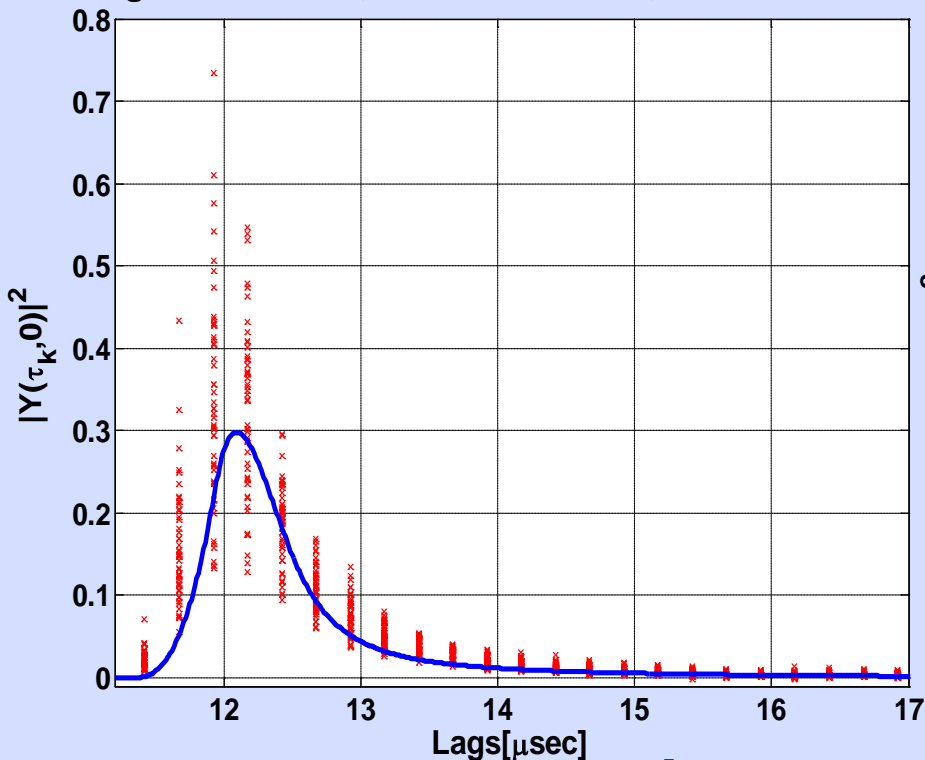


- **Sampling Frequency**
 - 8MHz
- **Coherent Integration**
 - 10ms
- **Incoherent Integration**
 - 1sec
- **Altitude**
 - 3,471 meters

Wind Retrieval (2010)

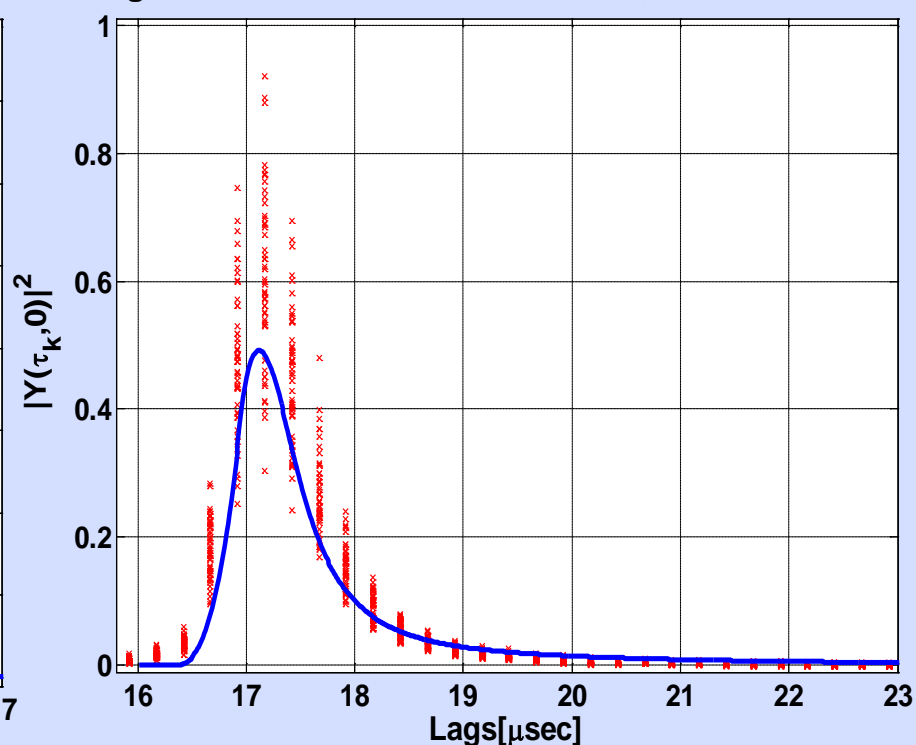
- Chesapeake Light (CHLV2): 7.5 m/s (MSS = 0.0010)

Flight Estimation, Elevation = 31.3°, Azimuth = 234.4°



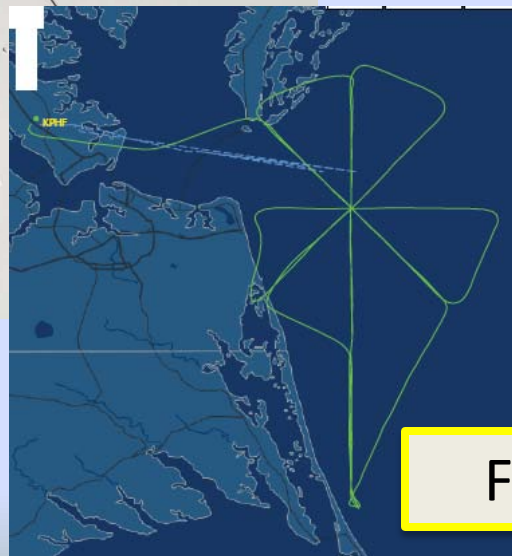
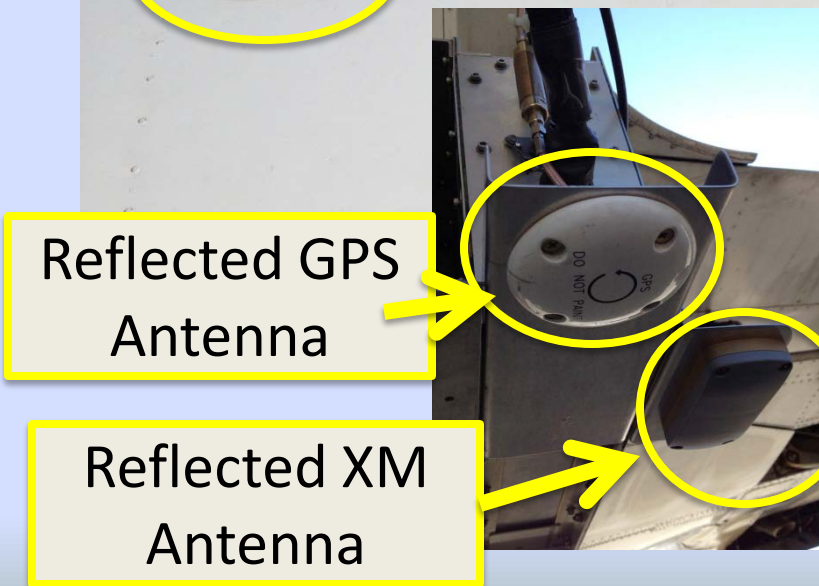
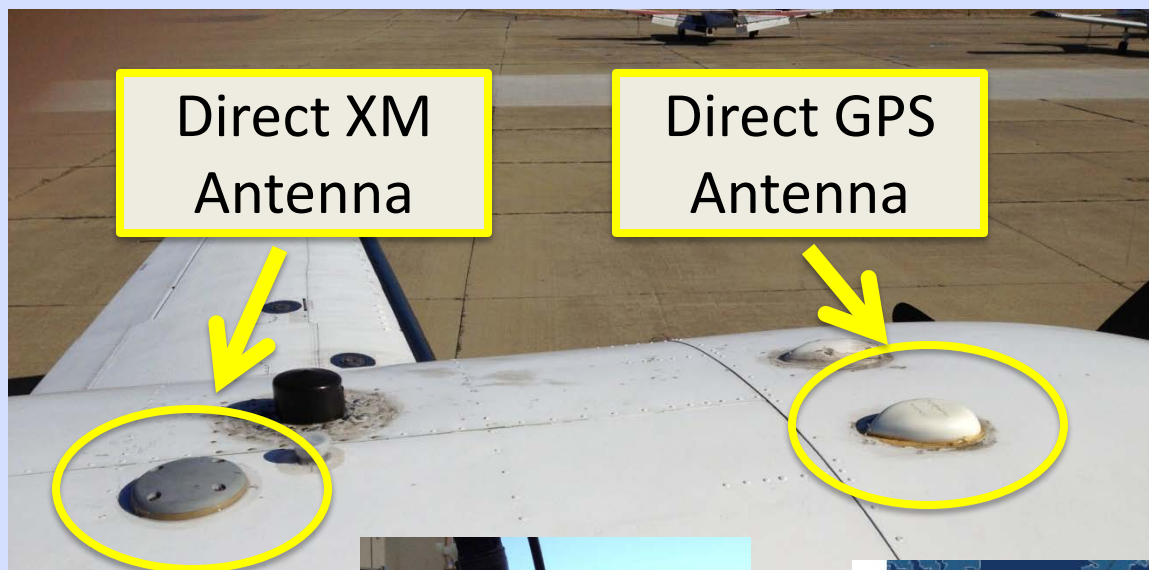
Blues: 6 m/s
(MSS = 0.0076)

Flight Estimation, Elevation = 46.3°, Azimuth = 196.4°



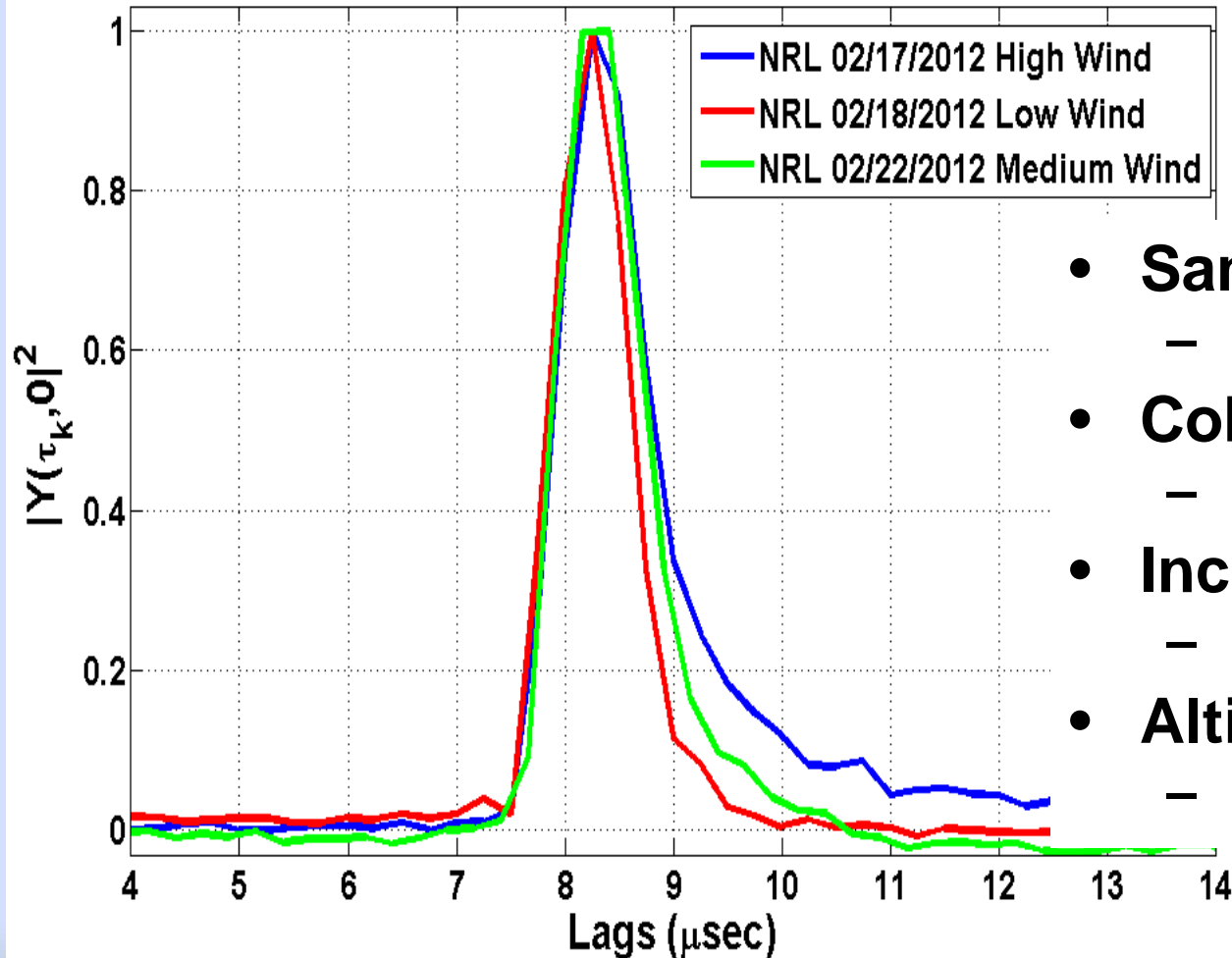
Rhythm: 7.2 m/s
(MSS=0.0098)

2012 Experiment



Waveforms (2012)

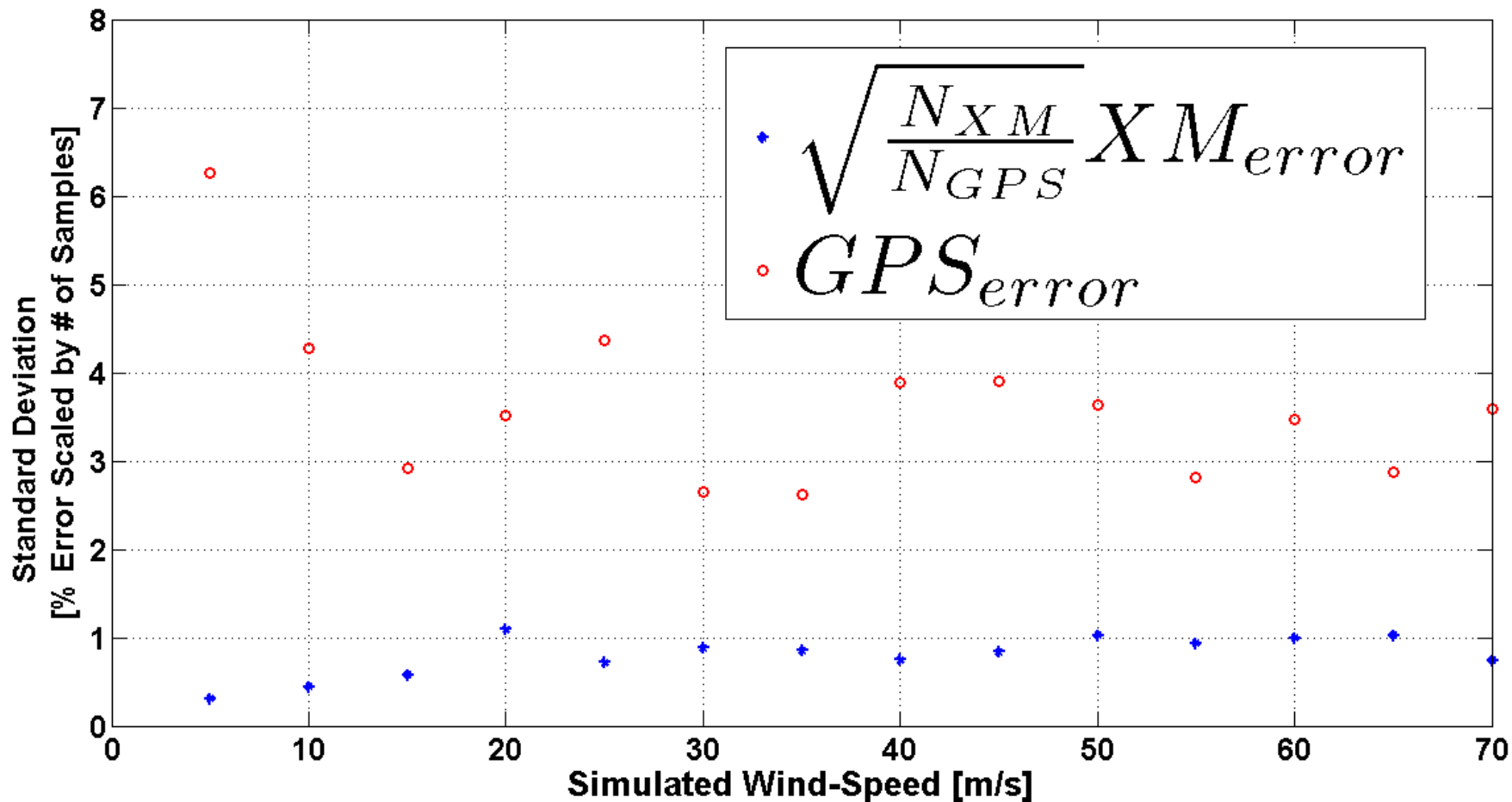
Waveform from NRL Flight Experiment



- **Sampling Frequency**
 - 4MHz
- **Coherent Integration**
 - 20ms
- **Incoherent Integration**
 - 2sec
- **Altitude**
 - 2,439 meters

Simulated Retrievals

Standard Deviation of Estimated MSS for XM, DirecTV and GPS



Flight Certified XM Instrument

ANTENNA



AMPLIFIER

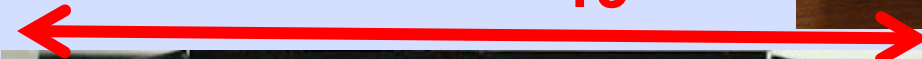


PC-104



USRP

19"



3U



FRONT VIEW



BACK VIEW

Summary

- GPS reflectometry heritage
- Recent demonstration with XM signal
 - +30 dB SNR increase
 - S-band vs. L-band
- Small, low power, autonomous instrumentation

Future Work (Proposed)

- Fly XM receiver during 2012 Hurricane Season

Acknowledgements

- Rashmi Shah was supported by the NASA Earth and Space Sciences Fellowship (NESSF), [Grant NNX11AL47H] and the Amelia Earhart Fellowship.
- The authors would also like to thank Derek Burrage and Joel Wesson of the Naval Research Laboratory (NRL) for inviting our participation in the 2012 experiment.
- Nicole Quindara's participation in the 2012 experiment was partially supported by NRL.
- Flights and aircraft installation were performed by Rick Aviation, Newport News, VA.

Thank you for your attention!

Questions ?

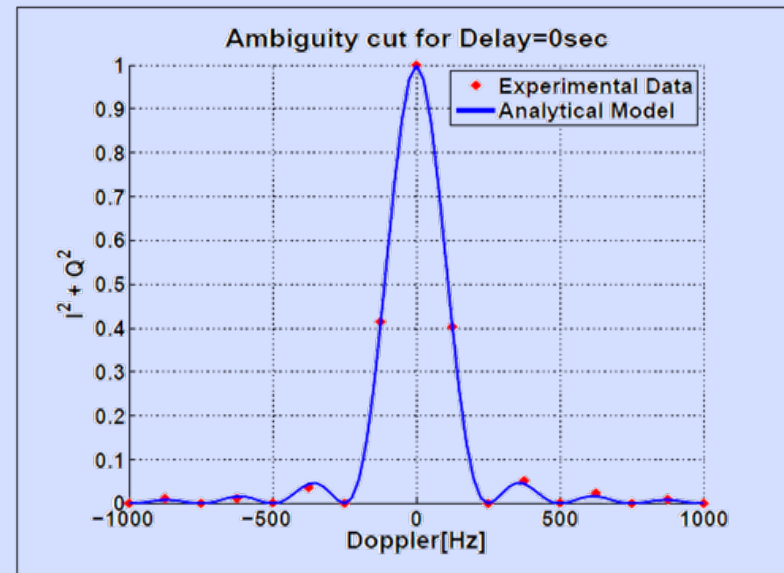
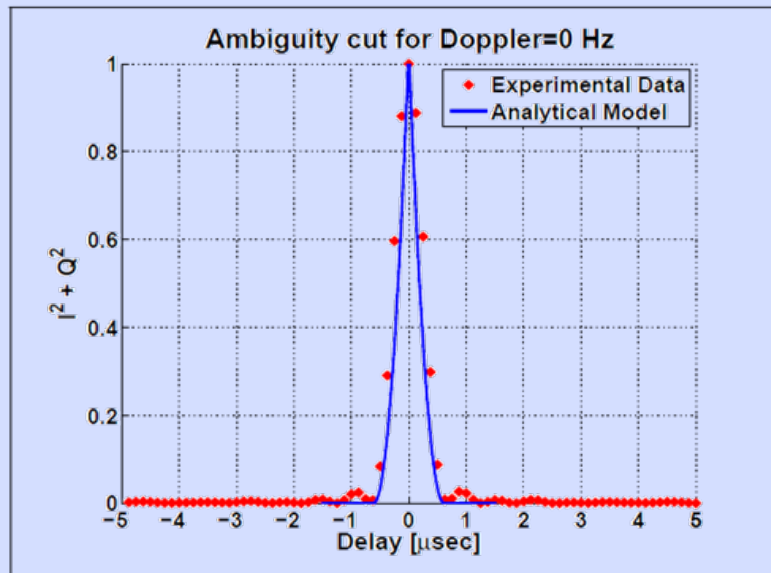
References

- J.L. Garrison, A. Komjathy, V.U. Zavorotny, and S.J. Katzberg, “Wind speed measurement using forward scattered GPS signals,” *IEEE Transactions on Geoscience and Remote Sensing*, vol. 40(1), pp. 50–65, 2002.
- J.L. Garrison, S.J. Katzberg, and M.I. Hill, “Effect of sea roughness on bistatically scattered range coded signals from the Global Positioning System,” *Geophys. Res. Lett*, vol. 25(13), pp. 2257–2260, 1998.
- E. Cardellach and A. Rius, “A new technique to sense non-Gaussian features of the sea surface from L-band bi-static GNSS reflections,” *Remote Sensing of Environment*, vol. 112, no. 6, pp. 2927 – 2937, 2008.
- R. Shah, J.L. Garrison, M.S. Grant, and S.J. Katzberg, Analysis of correlation properties of digital satellite signals and their applicability in bistatic remote sensing,” *Proceedings of the 2010 IEEE International Geoscience and Remote Sensing Symposium*, pp. 4114–4117, July 2010.
- S.J. Katzberg, O. Torres and G. Ganoë, “Calibration of reflected GPS for tropical storm wind speed retrievals,” *Geophys. Res. Lett*, vol. 33, L18602, 2006.

Backup Slides

XM: Ambiguity Function

$$|\chi(\tau, f_c)|^2 = \left| \frac{1}{T_I} \int_0^{T_I} s(t) s^*(t - \tau) e^{-j2\pi f_c t} dt \right|^2$$



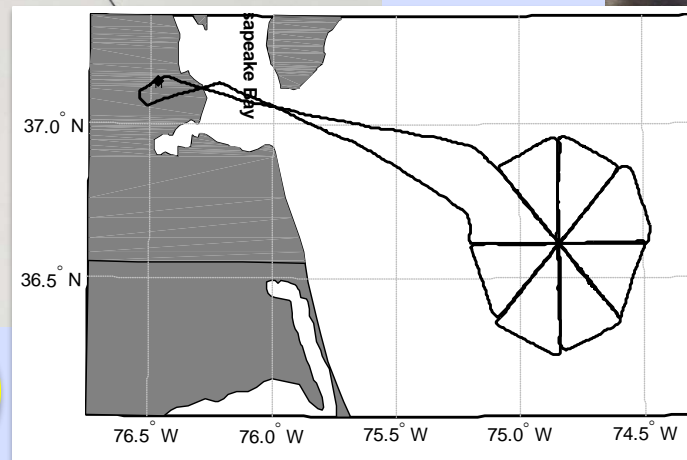
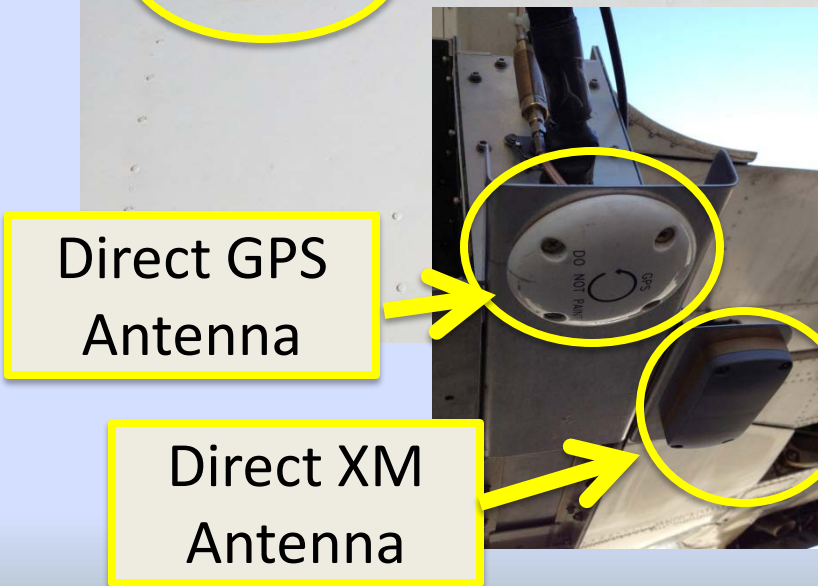
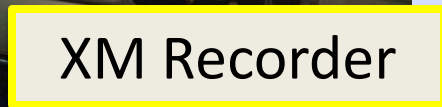
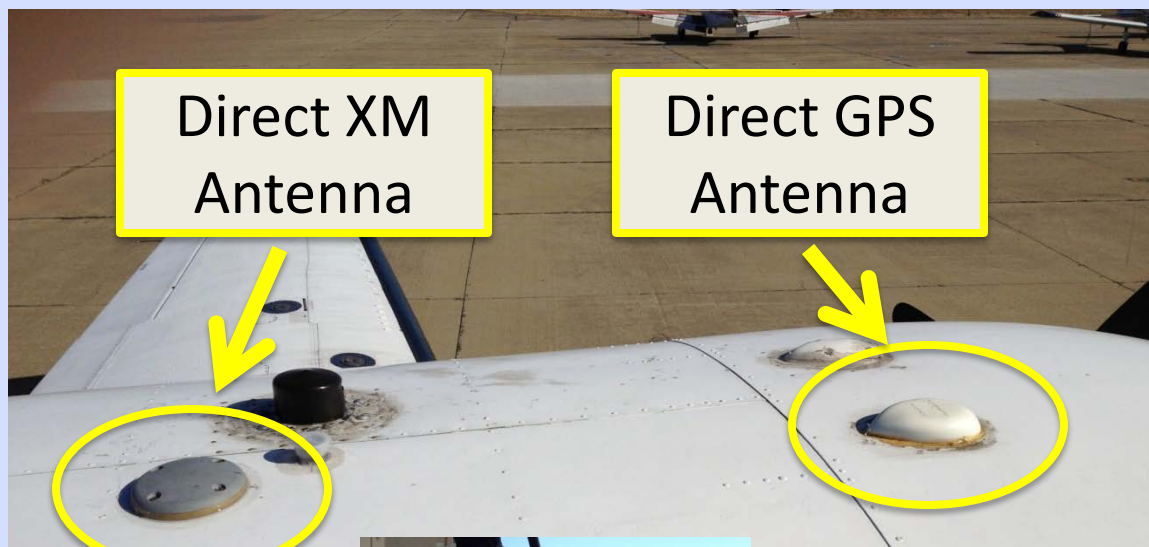
Delay Dimension $|\chi(\tau, 0)|^2$

Doppler Dimension $|\chi(0, f_c)|^2$

Assumption of long, random, uncorrelated data bit stream
validated

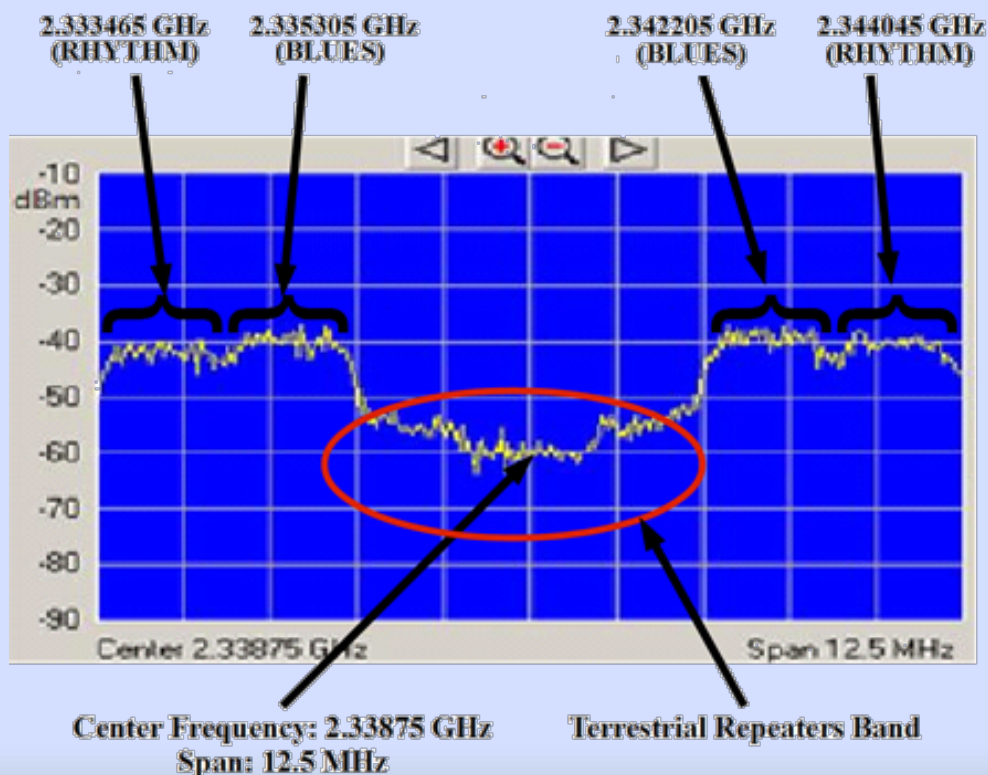
- **Global Navigation Satellite System Reflectometry (GNSS-R)**
 - First demonstration of remote sensing with “signals of opportunity”
 - Retrieval of ocean surface roughness, wind speed and direction
 - 12 Years of development: airborne (NOAA Hurricane Flights)
 - GNSS-R enabled by use of known pseudo-random noise (PRN) code
- **Digital Communication Signals Reflectometry**
 - Expand methods to other “signals of opportunity”
 - Demonstrated with XM digital radio
 - Commercial satellite radio system in the US

2012 Experiment

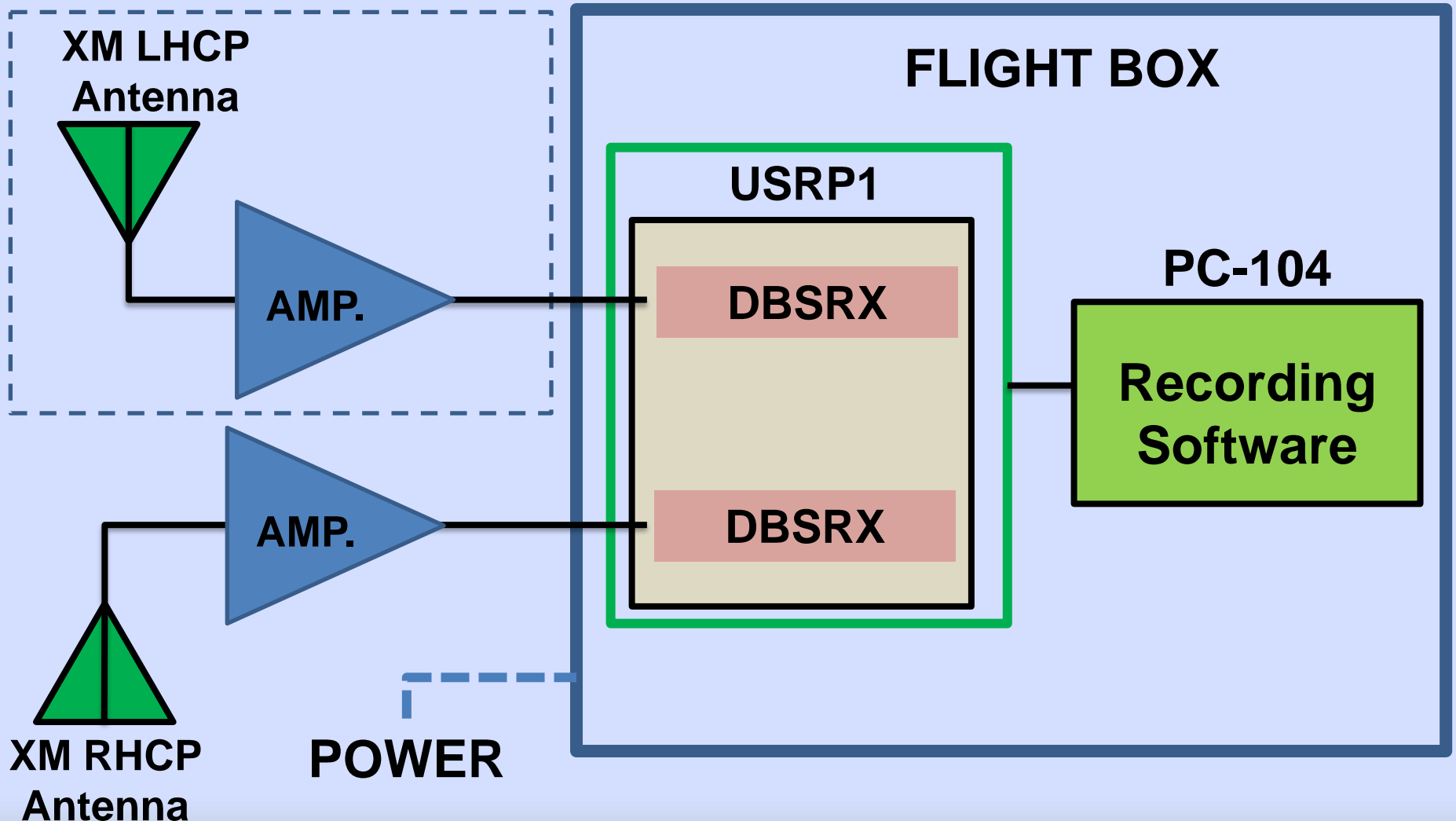


XM System

- **Two active geostationary satellites:**
 - Rhythm (85°W), Blues (115°W)
- **QPSK Modulated, LHCP Signal**



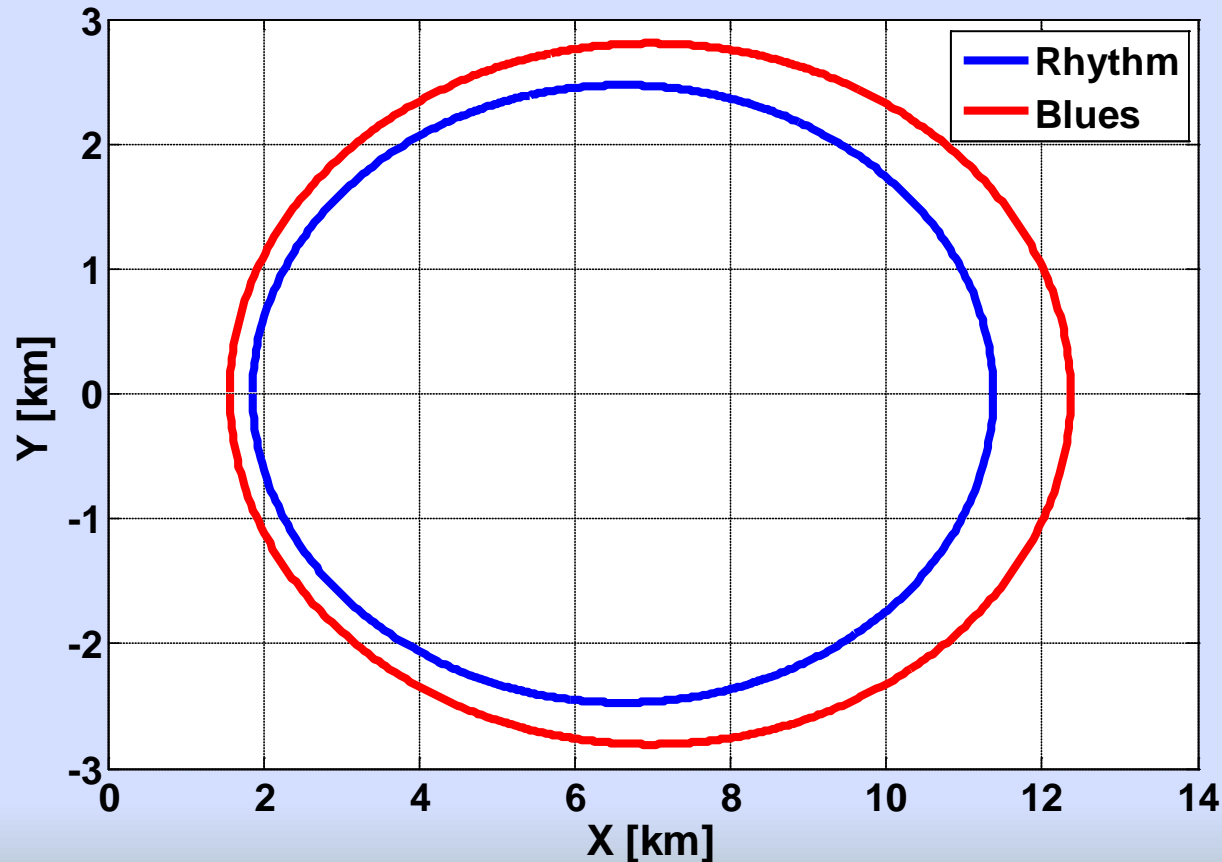
Instrument for NOAA Flights



Glistening Zone

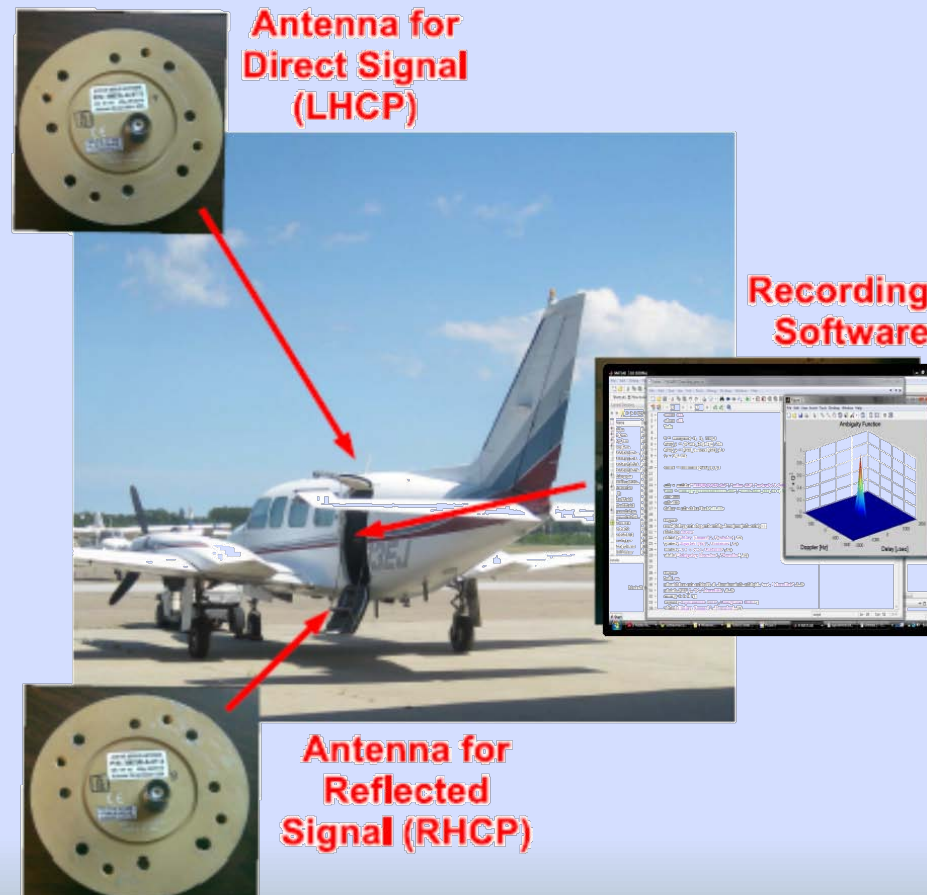
- **Blues:** Semi-major = 4.76km, Semi-minor = 2.47km
- **Rhythm:** Semi-major = 5.40km, Semi-minor = 2.80km

Glistening Zone



Airborne Experiment: Geometry

- Experiment conducted: 02-July-2010 in Piper Navajo
- Experiment time period: 07:51AM EDT - 09:19AM EDT



- Estimation process for Wind Speed
 - Isotropic normal PDF assumed
 - Nonlinear least squares estimation

$$J_{SV}(\mathbf{X}_{SV}) = \sum_k \left(|Y_{SV}(\tau_k, 0)|^2 - |Y_M(\tau_k, 0; \mathbf{X}_{SV})|^2 \right)^2$$
$$\mathbf{X}_{SV} = \{ \sigma^2_{ISO_{SV}}, S_{SV}, \tau_{0_{SV}} \}$$

$\sigma^2_{ISO_{SV}}$ = Mean Square Slope (MSS)

S_{SV} = Scale factor (remove variation in signal power)

$\tau_{0_{SV}}$ = Delay offset (adjust small uncertainties in delay)

- Independent estimate for each satellite

- Assume no bin-bin correlation
- Assume inphase and quadrature phase component to be independent normally distributed random variables
- Assume isotropic Gaussian distribution for PDF
 - $(\sigma_{ISO} = \sigma_u = \sigma_c)$

- Voltage signal:

$$Y_s(\tau, 0; P_{\vec{v}}) = \sqrt{\frac{|Y(\tau, 0; P_{\vec{v}})|^2}{2}} Z_s + \sqrt{\frac{N_0}{2T_I}} Z_n$$

- Synthetic Waveform

$$\langle |Y(\tau, 0; P_{\vec{v}})|^2 \rangle = \frac{1}{M} \sum_{i=1}^M Y_{s_i}(\tau, 0; P_{\vec{v}}) Y_{s_i}^*(\tau, 0; P_{\vec{v}})$$

Link Budget

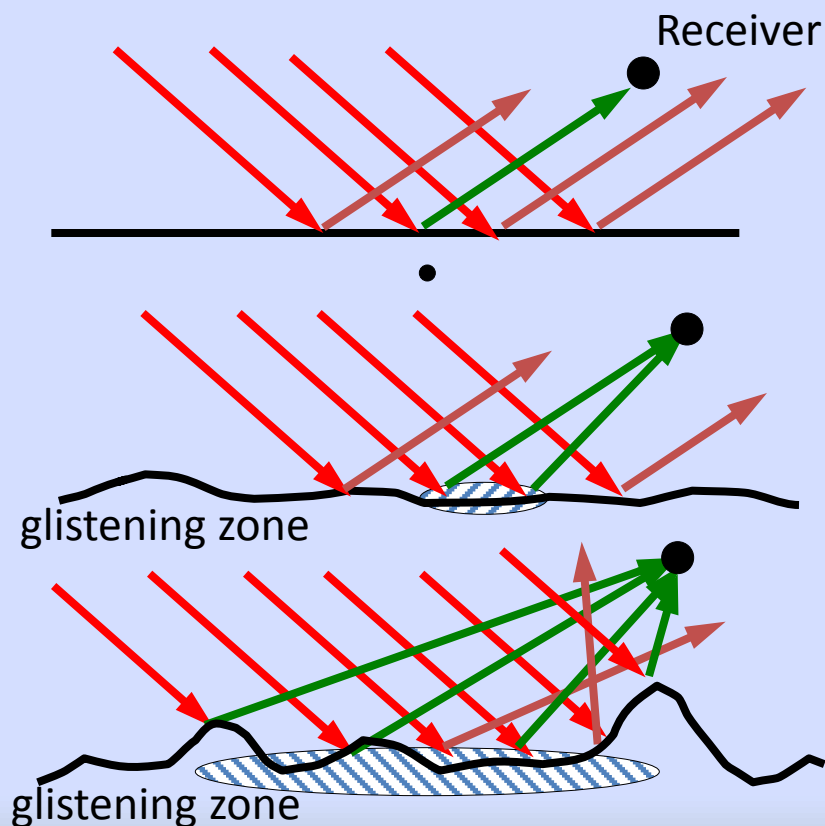
	XM (2)	GPS (1)	Unit
EIRP	68.5	26.3	dBW
Range	35888.0	22020.0	km
Path Loss	-162.1	-157.8	dB
Atmospheric loss	0.5	0.5	dB
Received Power Density	-94.1	-132.1	dBW/m ²
Effective Area	-28.8	-25.4	dBm ²
Received Isotropic Power	-122.9	-157.5	dBW
Antenna Gain	2.0	2.0	dBic
Received Signal Power	-120.9	-155.5	dBW
Noise Floor	-204.0	-204.0	dBW/Hz
C/N0	83.1	48.5	dB-Hz
Noise Figure	4.0	1.0	dB
Pre-Correlation, C/N0	79.1	47.5	dB-Hz
Bandwidth	62.7	63.1	dB-Hz
Pre-Correlation, S/N	16.4	-15.6	dB
Processing Gain	32.1	30.1	dB
Post Correlation, S/N	48.5	14.5	dB

Ocean Roughness/Wind Speed

Fundamental Physics:

Rougher surface =

larger distribution in path delays

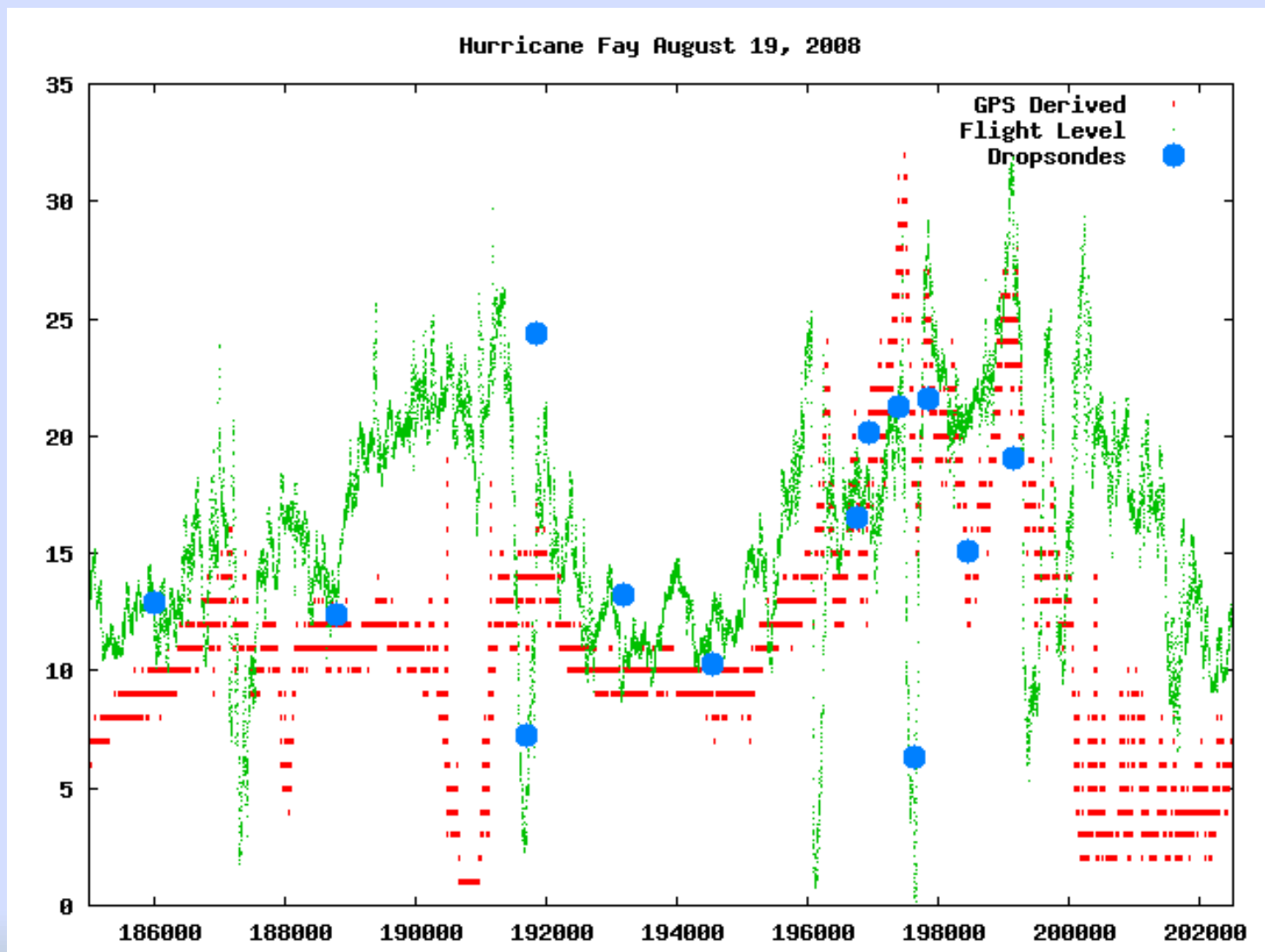


This phenomenon can easily be observed at sunset:
(water is calm inside the red ellipse)



(From Chapron and Ruffini, GNSS-R workshop, Barcelona. Photo taken at Le Conquet, Brittany)

GNSS-R Experience



GNSS-R Experience

- GNSS-R receivers on NOAA flights since 2000
- Calibration with wind speed up to Hurricane speeds.

